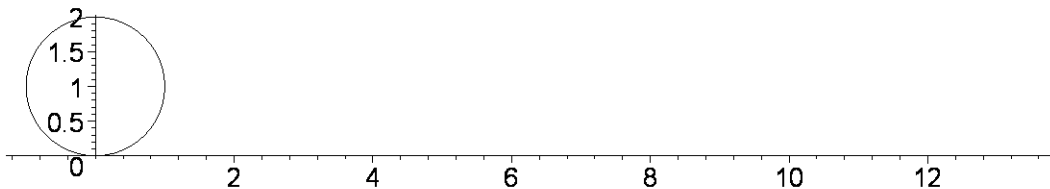


# Trochoida - pohyb hřebíku na kole

```
[ >
[ >
[ >
[ > with(plots):
[ >
[ > b:=1:
[ > fra:=50:rang:=0..4*Pi:
[ > A1:=animate([x-sin(t),1-cos(t),t=0..2*Pi],x=rang,frames=fra,color=BLACK,title=cat(`Trochoida pro b=`,convert(evalf(b),name))):
[ > A2:=animate([t*x-b*sin(t*x),1-b*cos(t*x),t=0..1],x=rang,frames=fra,color=RED):
[ > A3:=animate([t*x+(1-t)*(x-sin(x)),t+(1-t)*(1-cos(x)),t=1-b..1],x=0..4*Pi,frames=fra,color=BLUE):
[ > D1:=display({A2,A3}):display({A1,D1},scaling=constrained);
```

Trochoida pro b=1.

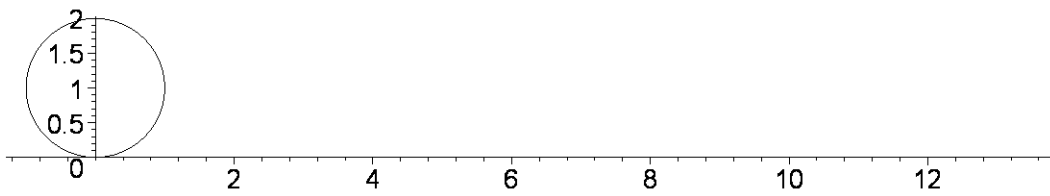


```
[ >
[ >
[ >
[ > b:=0.5:
```

```

[ > fra:=50:rang:=0..4*Pi:
[ > A1:=animate([x-sin(t),1-cos(t),t=0..2*Pi],x=rang,frames=fra,color=BLACK,title=cat(`Trochoida pro b=`,convert(evalf(b),name))):
[ > A2:=animate([t*x-b*sin(t*x),1-b*cos(t*x),t=0..1],x=rang,frames=fra,color=RED):
[ > A3:=animate([t*x+(1-t)*(x-sin(x)),t+(1-t)*(1-cos(x)),t=1-b..1],x=0..4*Pi,frames=fra,color=BLUE):
[ > D1:=display({A2,A3}):display({A1,D1},scaling=constrained);
                                Trochoida pro b=.5

```

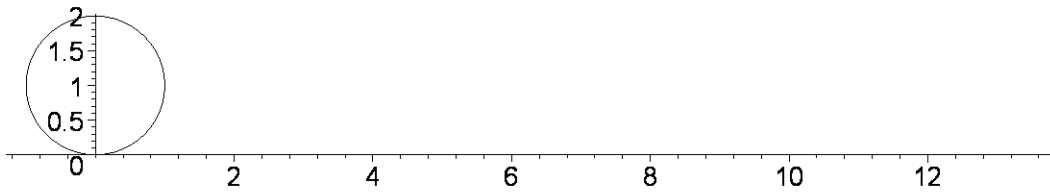


```

[ >
[ >
[ >
[ > b:=0.2:
[ > fra:=50:rang:=0..4*Pi:
[ > A1:=animate([x-sin(t),1-cos(t),t=0..2*Pi],x=rang,frames=fra,color=BLACK,title=cat(`Trochoida pro b=`,convert(evalf(b),name))):
[ > A2:=animate([t*x-b*sin(t*x),1-b*cos(t*x),t=0..1],x=rang,frames=fra,color=RED):
[ > A3:=animate([t*x+(1-t)*(x-sin(x)),t+(1-t)*(1-cos(x)),t=1-b..1],x=0..4*Pi,frames=fra,color=BLUE):
[ > D1:=display({A2,A3}):display({A1,D1},scaling=constrained);

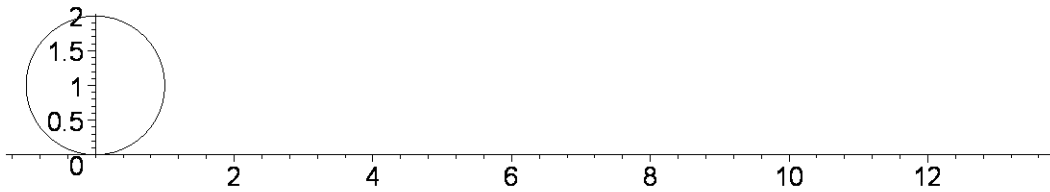
```

## Trochoida pro $b=2$



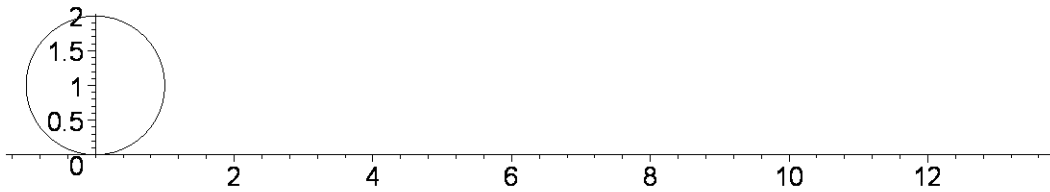
```
[ >
[ >
[ >
[ > b:=0:
[ > fra:=50:rang:=0..4*Pi:
[ > A1:=animate([x-sin(t),1-cos(t),t=0..2*Pi],x=rang,frames=fra,color=BLACK,title=cat(`Trochoida pro b=`,convert(evalf(b),name))):
[ > A2:=animate([t*x-b*sin(t*x),1-b*cos(t*x),t=0..1],x=rang,frames=fra,color=RED):
[ > A3:=animate([t*x+(1-t)*(x-sin(x)),t+(1-t)*(1-cos(x)),t=1-b..1],x=0..4*Pi,frames=fra,color=BLUE):
[ > D1:=display({A2,A3}):display({A1,D1},scaling=constrained);
```

Trochoida pro  $b=0$ .



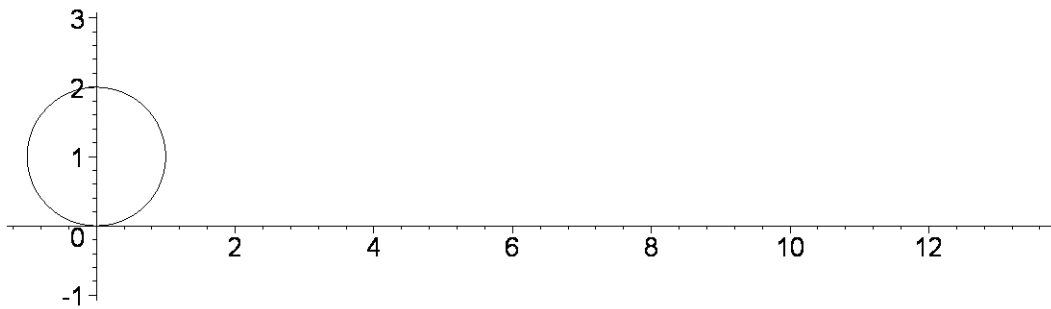
```
[ >
[ >
[ > b:=-1:
[ > fra:=50:rang:=0..4*Pi:
[ > A1:=animate([x-sin(t),1-cos(t),t=0..2*Pi],x=rang,frames=fra,color=BLACK,title=cat(`Trochoida pro b=`,convert(evalf(b),name))):
[ > A2:=animate([t*x-b*sin(t*x),1-b*cos(t*x),t=0..1],x=rang,frames=fra,color=RED):
[ > A3:=animate([t*x+(1-t)*(x-sin(x)),t+(1-t)*(1-cos(x)),t=1-b..1],x=0..4*Pi,frames=fra,color=BLUE):
[ > D1:=display({A2,A3}):display({A1,D1},scaling=constrained);
```

Trochoida pro  $b=-1$ .



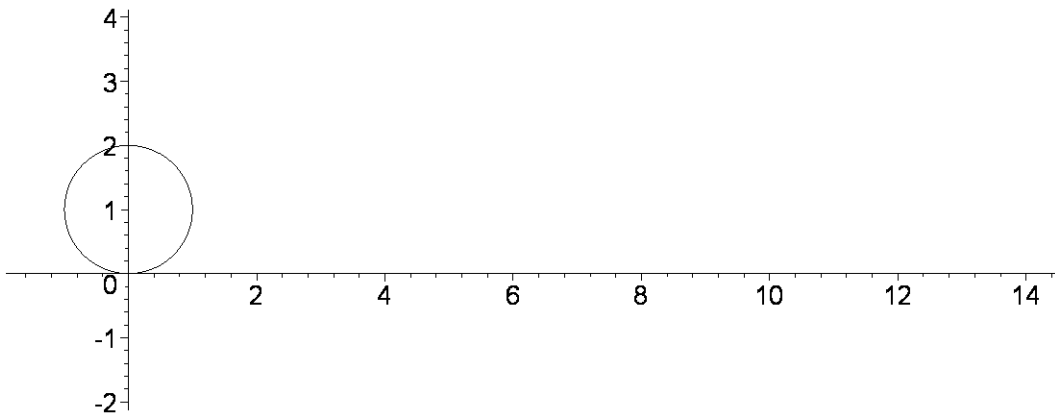
```
[ > b:=2:
[ >
[ >
[ >
[ > fra:=50:rang:=0..4*Pi:
[ > A1:=animate([x-sin(t),1-cos(t),t=0..2*Pi],x=rang,frames=fra,color=BLACK,title=cat(`Trochoida pro b=`,convert(evalf(b),name))):
[ > A2:=animate([t*x-b*sin(t*x),1-b*cos(t*x),t=0..1],x=rang,frames=fra,color=RED):
[ > A3:=animate([t*x+(1-t)*(x-sin(x)),t+(1-t)*(1-cos(x)),t=1-b..1],x=0..4*Pi,frames=fra,color=BLUE):
[ > D1:=display({A2,A3}):display({A1,D1},scaling=constrained);
```

Trochoida pro b=2.



```
[ >
[ >
[ > b:=3:
[ > fra:=50:rang:=0..4*Pi:
[ > A1:=animate([x-sin(t),1-cos(t),t=0..2*Pi],x=rang,frames=fra,color=BLACK,title=cat(`Trochoida pro b=`,convert(evalf(b),name))):
[ > A2:=animate([t*x-b*sin(t*x),1-b*cos(t*x),t=0..1],x=rang,frames=fra,color=RED):
[ > A3:=animate([t*x+(1-t)*(x-sin(x)),t+(1-t)*(1-cos(x)),t=1-b..1],x=0..4*Pi,frames=fra,color=BLUE):
[ > D1:=display({A2,A3}):display({A1,D1},scaling=constrained);
```

Trochoida pro  $b=3$ .



[ >  
[ >