

Pracovní list k animacím o funkcích a derivacích. V rámci predmetu PRM 039 Matematika na počítání vytvořil Dominik Mokris, připraveno k odevzdání 15.9.2008.

```
> #pracovní list je připraven k použití, stačí execute the  
worksheet. v případě spuštění procedur samostatně  
#je třeba nejprve odenterovat první dva řádky (oba začínají  
with). Obrazky je vhodno roztáhnout do šířky,  
#vypadají pak líp. Příjemné počítání :-)
```

```
> with(plottools);
```

```
[arc, arrow, circle, cone, cuboid, curve, cutin, cutout, cylinder, disk, dodecahedron, ellipse,  
ellipticArc, hemisphere, hexahedron, homothety, hyperbola, icosahedron, line, octahedron,  
parallelepiped, pieslice, point, polygon, project, rectangle, reflect, rotate, scale, semitorus,  
sphere, stellate, tetrahedron, torus, transform, translate]
```

```
>
```

```
> with(plots):
```

```
> H0 := proc(t)
```

```
plots[display](
```

```
point([1,Pi],color=blue),
```

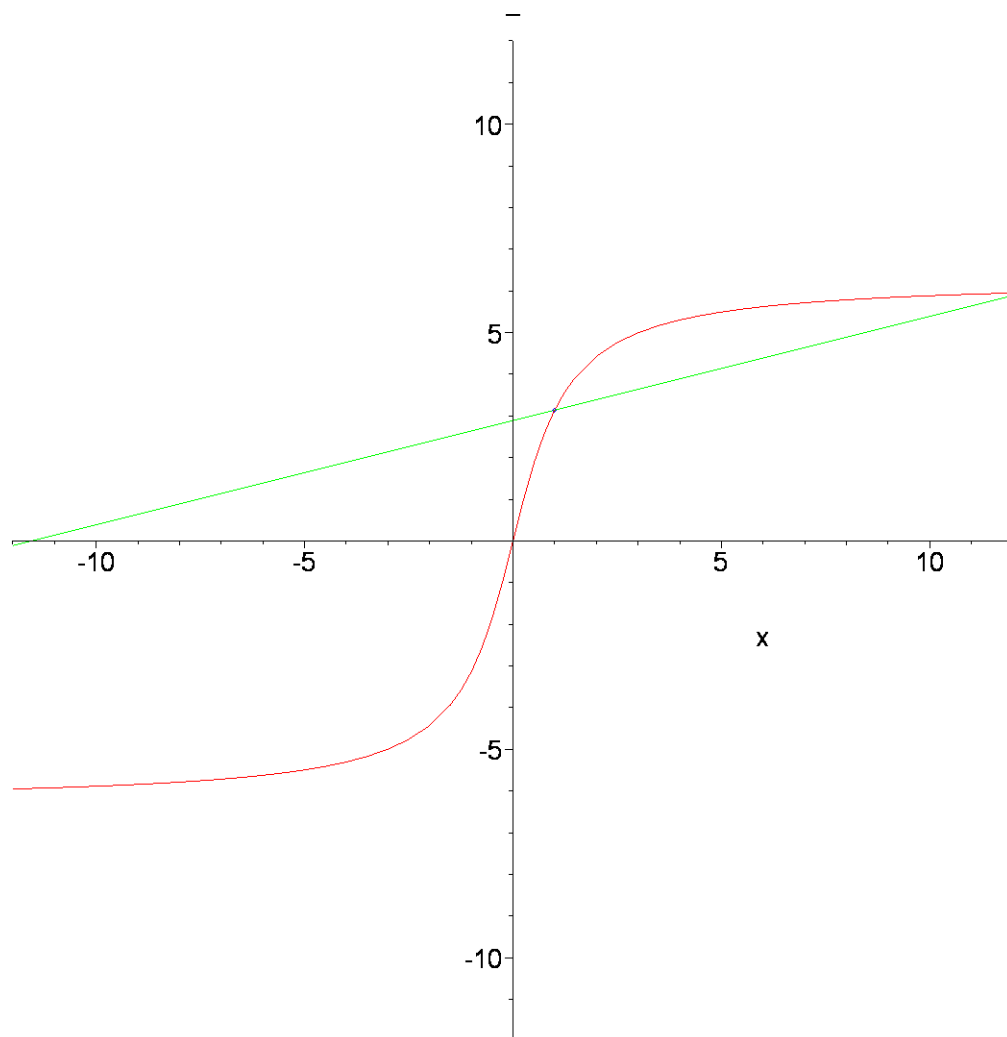
```
plot(4*arctan(x),x=-12..12, color=red, view=-12..12),
```

```
plot(Pi+t*(x-1),x=-12..12, color=green, view=-5..5));
```

```
end:
```

```
animate(H0,[theta], theta=.25..2,title='_', frames=50);
```

```
>
```



```

> H1 := proc(t)
plots[display](
  line([-7,0],[7,0], color = black),#osa x vlevo
  line([8,0],[22,0], color = black),#osa x vpravo
  line([0,-5],[0,5], color = black),#osa y vlevo
  line([15,-5],[15,5], color = black),#osa y vpravo

point([t+15,(1/3)*(exp((t)/3)*cos(3*(t)))-3*exp((t)/3)*sin(3*(t)
)], color = blue),
  point([t,exp(t/3)*cos(3*t)], color = blue),

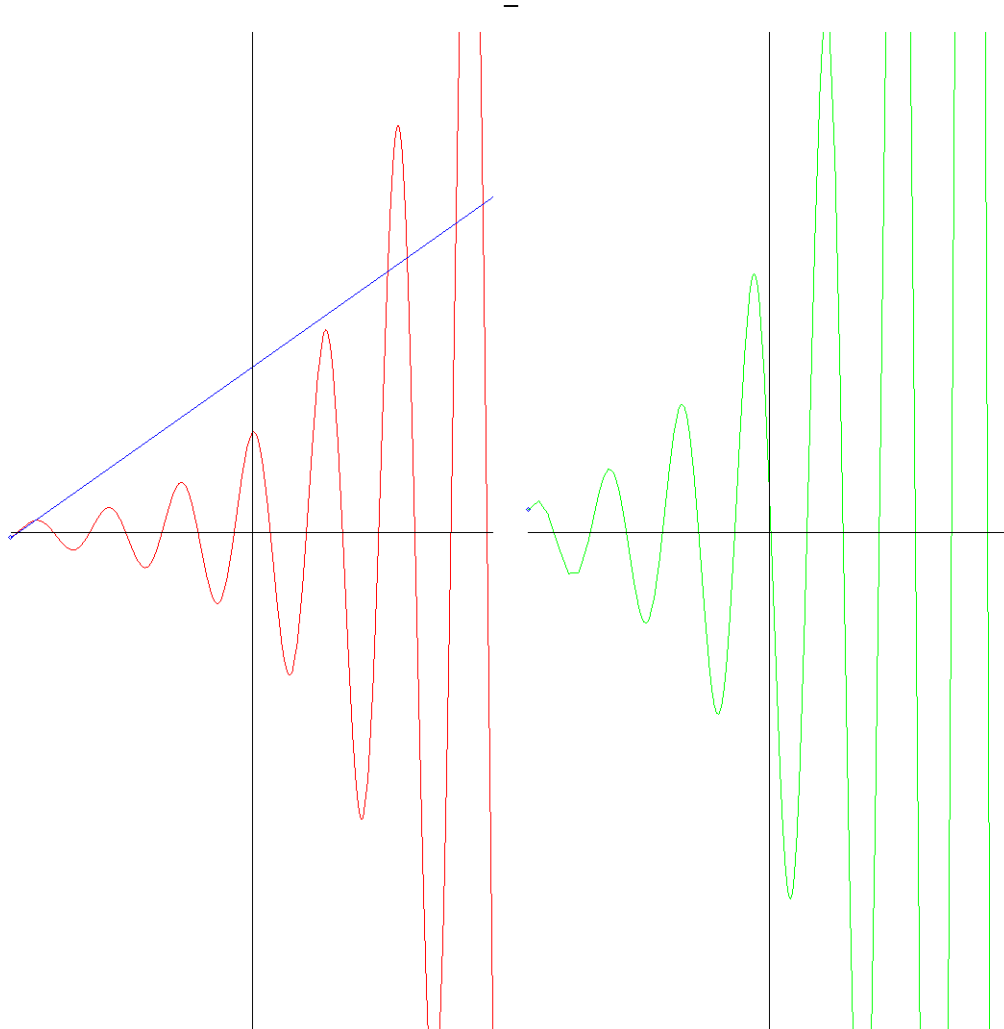
plot((1/3)*(exp(t/3)*cos(3*t))-3*exp(t/3)*sin(3*(t))*(x-t)+(2/3)
*exp(t/3)*cos(3*t),x=-7..7, color=blue, view=-5..5),
  #nechapu, proc ty dve tretiny, ale funguje to, rekl bych, je
to ta modra tecna
  plot(exp(x/3)*cos(3*x),x=-7..7, color=red, view=-5..5),

plot((1/3)*(exp((x-15)/3)*cos(3*(x-15)))-3*exp((x-15)/3)*sin(3*(
x-15)),x=8..22, color=green, view=-5..5));
end:

```

```
animate(H1,[theta], theta=-7..7, axes=none, title = '_',
frames=120);
```

```
>
>
```



```
> with(plottools):
```

```
> H2 := proc(t)
```

```
plots[display](
```

```
  line([-7,0],[7,0], color = black),#osa x vlevo
```

```
  line([8,0],[22,0], color = black),#osa x vpravo
```

```
  line([0,-5],[0,5], color = black),#osa y vlevo
```

```
  line([15,-5],[15,5], color = black),#osa y vpravo
```

```
  line([17,-5],[17,5],color=blue, linestyle=3),
```

```
  circle([17,0],.1,color=blue),#krouzek kolem mista extremu
```

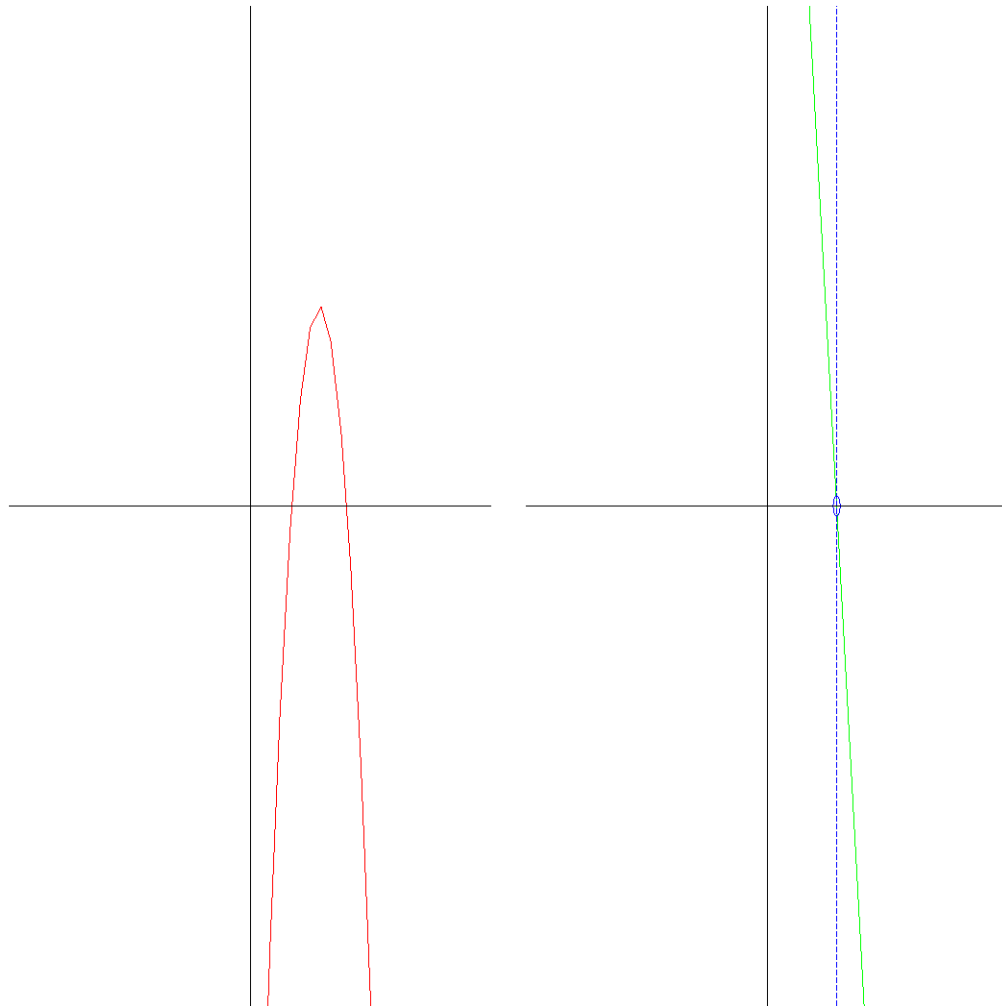
```
  plot(piecewise(t<=0, t*(x-2)^2 + 2 , t>0,
t*abs(x-2)+2),x=-7..7, color=red, view=-5..5),
```

```
  plot(piecewise(t<=0,t*(2*(x-16)-2),t>0,piecewise(x<17,-(t),x>17,
t)),x=8..22,color=green,view=-5..5));
```

```
end:
```

```
animate(H2,[theta], theta=-Pi..Pi, axes=none, title='_',
```

```
frames=120);
```



Tolik ilustrace Fermatovy Vety, pekne, ne? Akorat to dela svislou zelenou caru, nepodarilo se mi to vypnout. Ale takhle to neni moc videt :-]

```
[ >
```

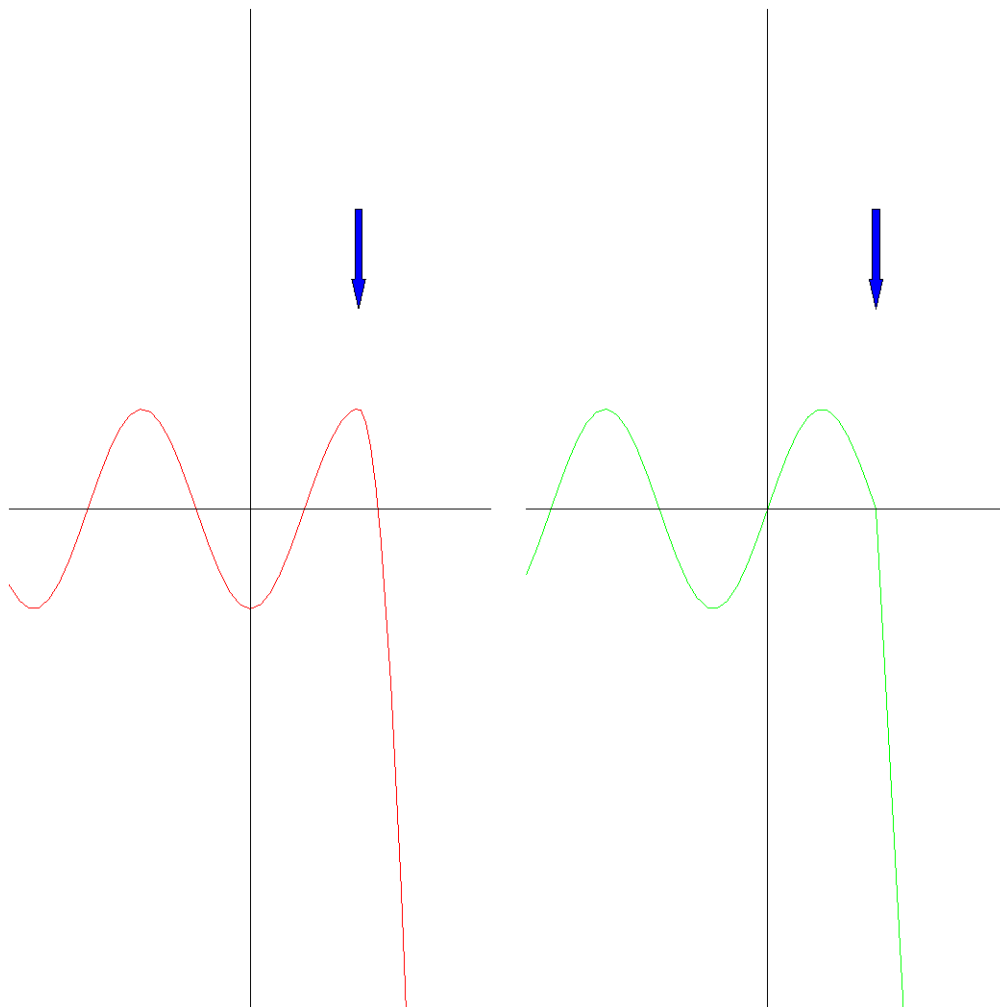
```
> H3 := proc(t)
  plots[display](
    line([-7,0],[7,0], color = black),#osa x vlevo
    line([8,0],[22,0], color = black),#osa x vpravo
    line([0,-5],[0,5], color = black),#osa y vlevo
    line([15,-5],[15,5], color = black),#osa y vpravo
    arrow([Pi,3],[Pi,2],.2,.4,.3, color = blue),#sipka vlevo

    arrow([15+Pi,3],[15+Pi,2],.2,.4,.3, color = blue),#sipka
vpravo
    plot(piecewise(x<=Pi+15,sin(x-15), x > Pi+15
,t*(2*(x-15)-2*Pi)),x=8..22, color=green, view=-5..5),
    plot(piecewise(x<Pi, -cos(x), x >= Pi ,t*(x-Pi)^2 +
1),x=-7..7, color=red, view=-5..5));
  end:
  animate(H3,[theta], theta=-Pi..Pi, axes=none, title='_',
```

```
frames=120);
```

Takhle se mi to libi, myslim, ze to je docela nazorne.

>



```
> with(plottools);
```

```
> H4 := proc(t)
```

```
plots[display](
```

```
    line([-7,0],[7,0], color = black),#osa x vlevo
```

```
    line([8,0],[22,0], color = black),#osa x vpravo
```

```
    line([0,-5],[0,5], color = black),#osa y vlevo
```

```
    line([15,-5],[15,5], color = black),#osa y vpravo
```

```
    plot(sin(2*x)*cos(x) + 3*sin(t)*cos(2*t),x=-7..7,  
color=red, view=-5..5),
```

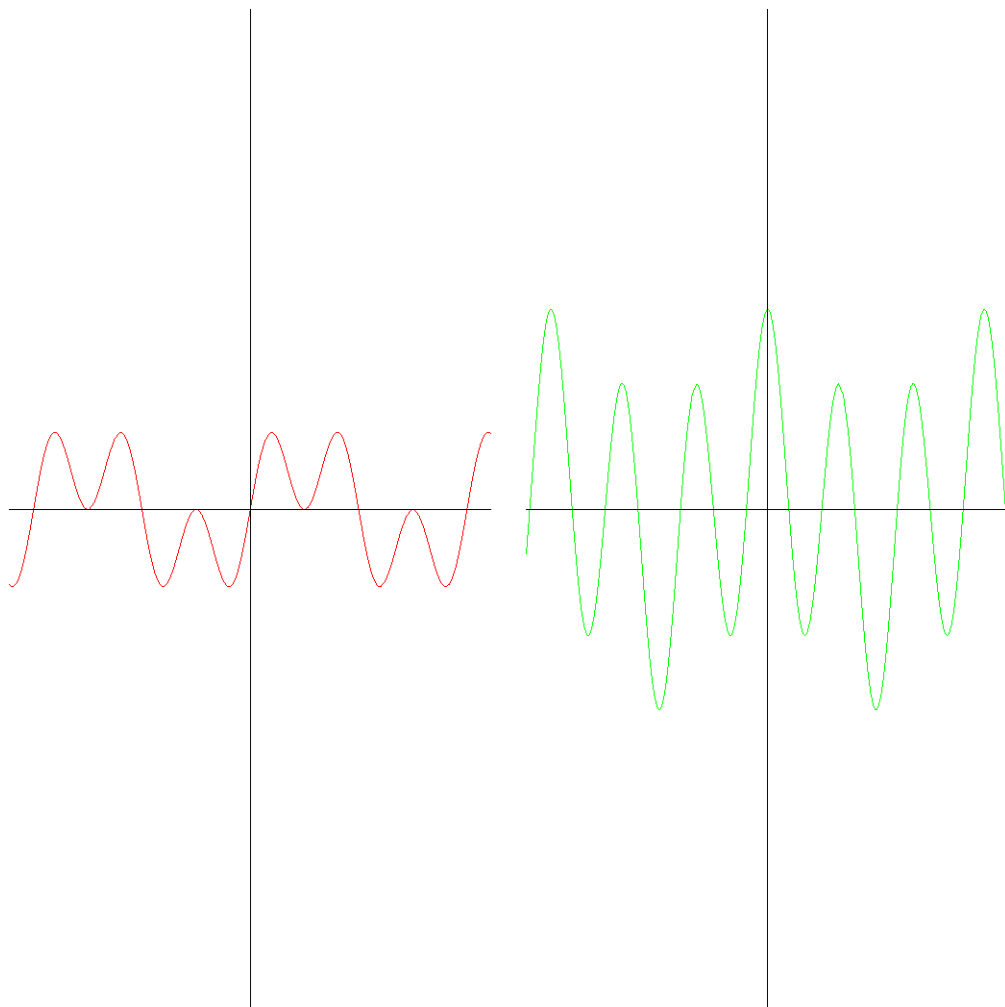
```
    plot(cos(2*(x-15))*2*cos(x-15)-sin(2*(x-15))*sin(x-15),x=8..22,c  
olor=green, view=-5..5));
```

```
end:
```

```
animate(H4,[theta], theta=-Pi..Pi, axes=none, title='_',  
frames=150);
```

[arc, arrow, circle, cone, cuboid, curve, cutin, cutout, cylinder, disk, dodecahedron, ellipse,

ellipticArc, hemisphere, hexahedron, homothety, hyperbola, icosahedron, line, octahedron, parallelepiped, pieslice, point, polygon, project, rectangle, reflect, rotate, scale, semitorus, sphere, stellate, tetrahedron, torus, transform, translate]



Vidime, ze posun ve smeru osy y nic nemeni na derivaci.

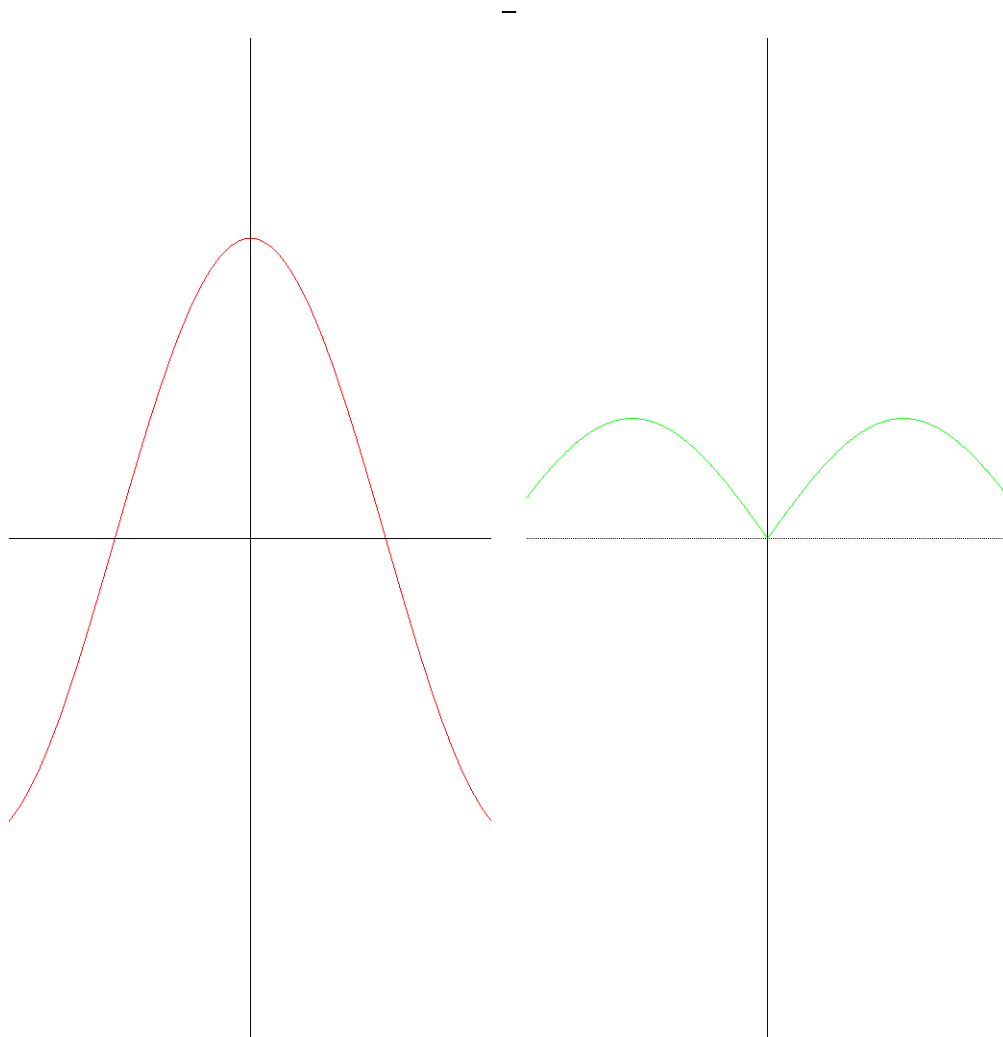
```
> with(plottools):
> H5 := proc(t)
plots[display](
    line([-7,0],[7,0], color = black),#osa x vlevo
    line([8,0],[22,0], color = black, linestyle=2),#osa x vpravo,
    tentokrat pro prehlednost teckovane
    line([0,-5],[0,5], color = black),#osa y vlevo
    line([15,-5],[15,5], color = black),#osa y vpravo

    plot(piecewise(x<-3*sin(t),3*cos(.4*(x+3*sin(t))),x>3*sin(t),3*cos(.4*(x-3*sin(t))), 3),x=-7..7, color=red, view=-5..5),
    # musi mit stejne parametru, jinak se zobrazi jen jeden

    plot(piecewise(x<15-3*sin(t),-1.2*sin(.4*(x-15+3*sin(t))),x>15+3*sin(t),1.2*sin(.4*(x-15-3*sin(t))),0),
    x=8..22,color=green,view=-5..5));
```

```
end:
animate(H5,[theta], theta=0..Pi, axes=none, title='_');
```

>



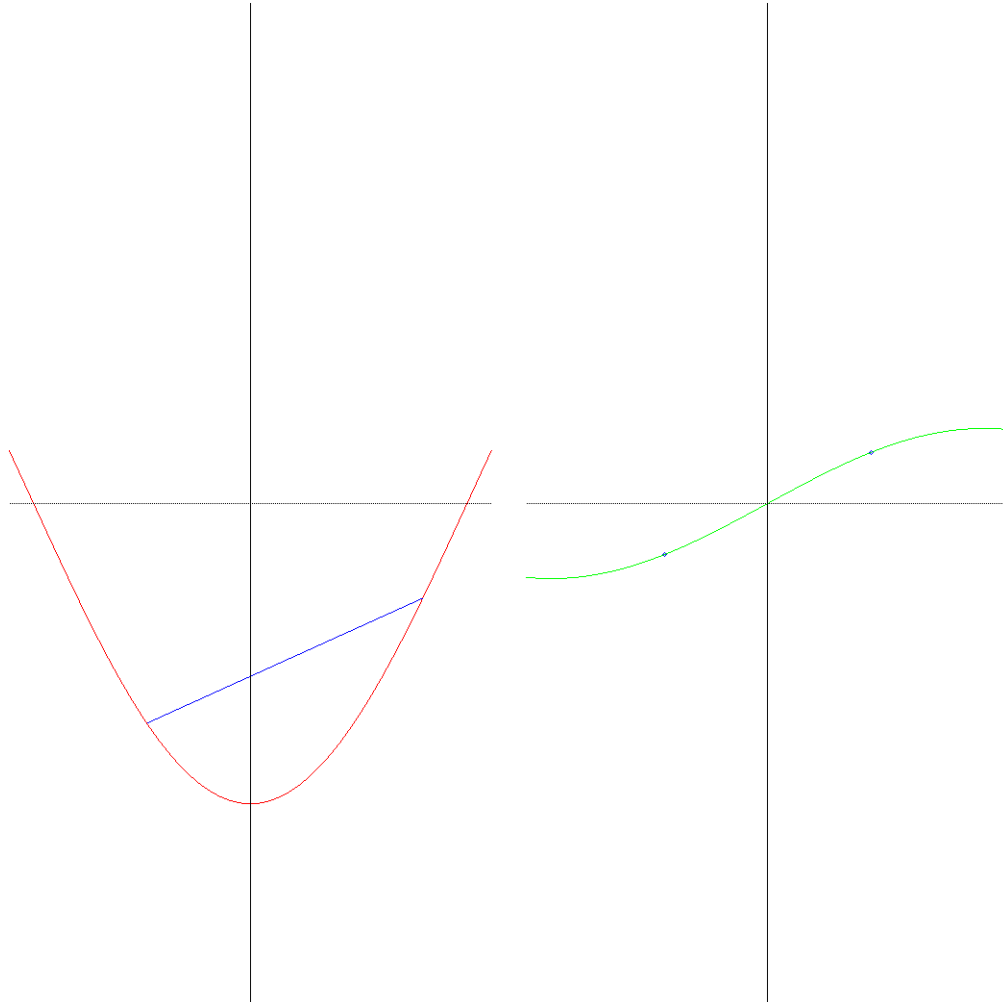
Tedy pokud ma funkce na nejakem intervalu nulovou derivaci, je na nem konstantni. Pokud je kladna derivace, funkce stoupa, pokud je zaporna, derivace klesa. Dalo to zabrat.

```
> H6 := proc(t)
plots[display](
  line([-7,0],[7,0], color = black, linestyle=2),#osa x vlevo
  line([8,0],[22,0], color = black, linestyle=2),#osa x vpravo,
tentokrat pro prehlednost teckovane
  line([0,-5],[0,5], color = black),#osa y vlevo
  line([15,-5],[15,5], color = black),#osa y vpravo
  line([-3,-3*cos(t)*cos(-3/4)],[5,-3*cos(t)*cos(5/4)], color =
blue),
  point([12,3*cos(t)/4*sin(-3/4)], color = blue),
  point([18,3*cos(t)/4*sin(3/4)], color = blue),
  plot(-3*cos(t)*cos(x/4),x=-7..7, color=red, view=-5..5),
# musi mit stejne parametru, jinak se zobrazi jen jeden
```

```

    plot((3*cos(t)/4)*sin((x-15)/4),
x=8..22,color=green,view=-5..5);
end:
animate(H6,[theta], theta=0..2*Pi, axes=none, title='_',
frames=76);

```



```

> H7 := proc(t)
plots[display](
    line([-7,0],[7,0], color = black),#osa x vlevo
    line([8,0],[22,0], color = black),#osa x vpravo
    line([0,-5],[0,5], color = black),#osa y vlevo
    line([15,-5],[15,5], color = black),#osa y vpravo
    plot(exp(abs(x))*cos(4*x*sin(t))/74,x=-7..7, color=red,
view=-5..5),
# musi mit stejne parametru, jinak se zobrazi jen jeden

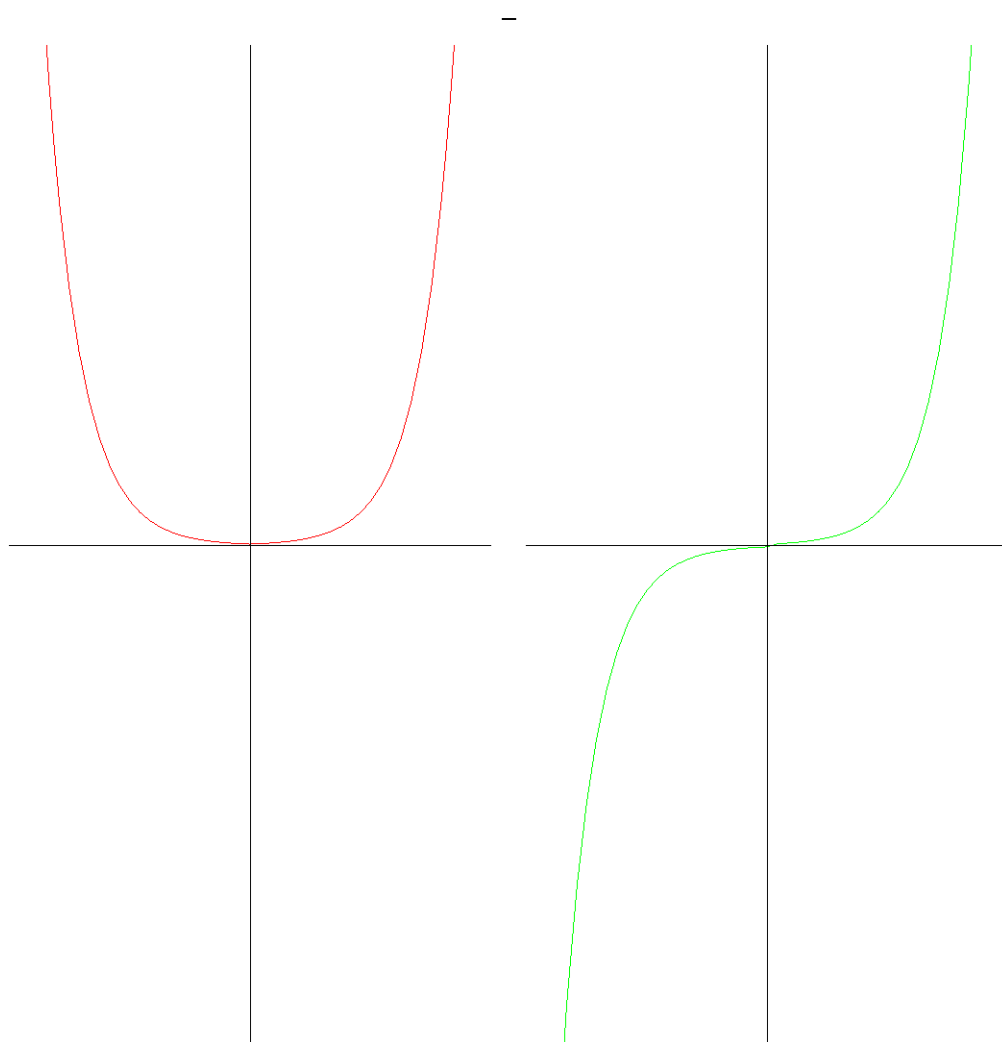
plot(1/74*abs(1,x-15)*exp(abs(x-15))*cos(4*(x-15)*sin(t))-2/37*e
xp(abs(x-15))*sin(4*(x-15)*sin(t))*sin(t),
x=8..22,color=green,view=-5..5));
end:
animate(H7,[theta], theta=0..Pi, axes=none, title='_',

```



```
frames=120);
```

```
>
```



```
> H8 := proc(t)
```

```
plots[display](
```

```
  line([-7,0],[7,0], color = black, linestyle = 2),#osa x vlevo
```

```
  line([8,0],[22,0], color = black, linestyle = 2),#osa x
```

```
vpravo
```

```
  line([0,-5],[0,5], color = black),#osa y vlevo
```

```
  line([15,-5],[15,5], color = black),#osa y vpravo
```

```
  plot(sin(t)*sinh(x),x=-7..7, color=red, view=-5..5),
```

```
# musi mit stejne parametru, jinak se zobrazi jen jeden
```

```
  plot(sin(t)*cosh(x-15), x=8..22,color=green,view=-5..5));
```

```
end:
```

```
animate(H8,[theta], theta=0..2*Pi, axes=None, title='_',
```

```
frames=132);
```

```
> prusecik := 4*arctan(x)=Pi+(x-1)*t;
```

$$\text{prusecik} := 4 \arctan(x) = \pi + (x - 1) t$$

```
> solve(prusecik,x);
```

$$\frac{4 \operatorname{RootOf}(-\tan(_Z) t + 4 _Z - \pi + t) - \pi + t}{t}$$

```
> evalf(%);
```

$$\frac{4. \operatorname{RootOf}(-\tan(_Z) t + 4 _Z - \pi + t) - 3.141592654 + t}{t}$$

Myslel jsem, ze to budou dva body a budou se priblizovat. V nulte animaci.

```
> H9 := proc(t)
```

```
plots[display](
```

```
  line([-7,0], [7,0], color = black),#osa x vlevo  
  line([8,0], [22,0], color = black),#osa x vpravo  
  line([0,-5], [0,5], color = black),#osa y vlevo  
  line([15,-5],[15,5], color = black),#osa y vpravo  
  line([23,0], [39,0], color = black),  
  line([31,-5],[31,5], color = black),
```

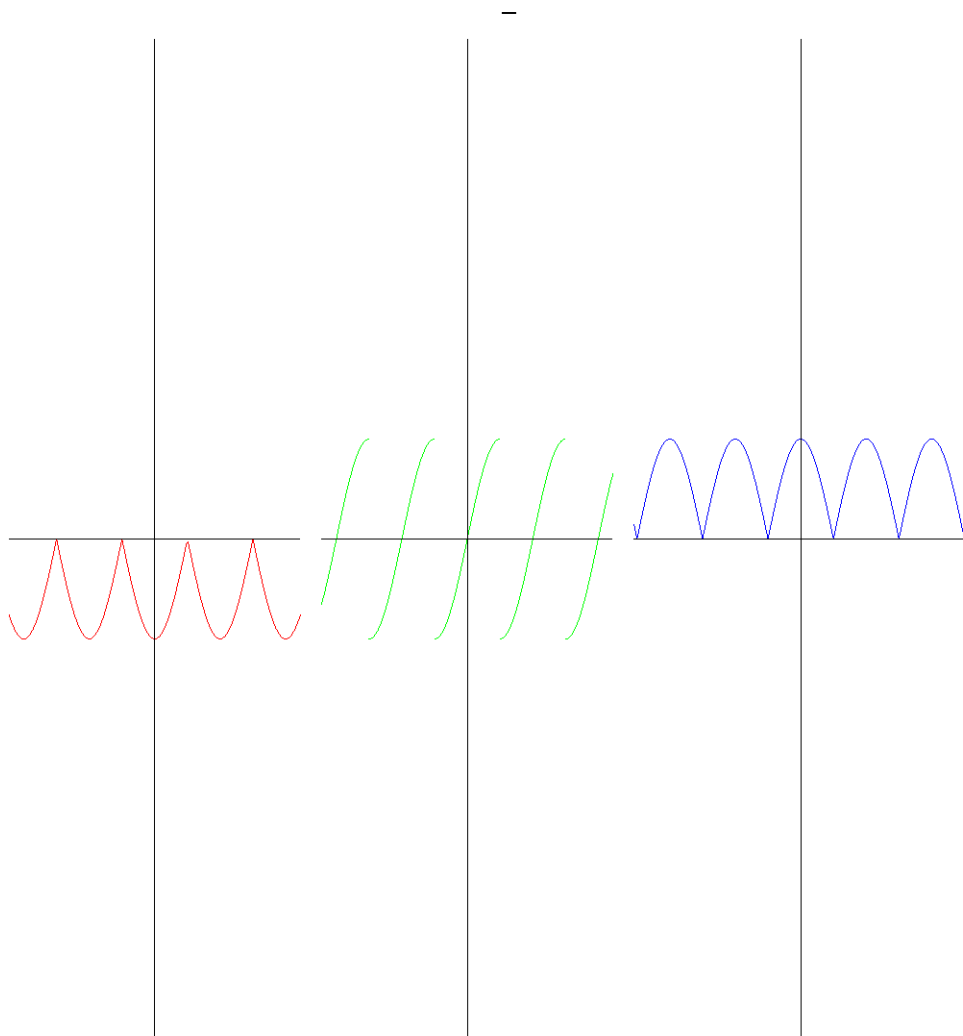
```
  plot(sin(t)*sin(x)-abs(cos(x)), x=-7..7, color = red, view=  
-5..5, discontinuous=true),
```

```

    plot(sin(t)*cos(x-15)+abs(1,cos(x-15))*sin(x-15),x=8..22,
color = green, view=-5..5, discontinuous=true),

plot(-sin(t)*sin(x-31)+signum(1,cos(x-31))*sin(x-31)+abs(1,cos(x
-31))*cos(x-31),x=23..39, color = blue, view=-5..5,
discontinuous=true),
    plot(sin(x),x=40..41, color = white, view=-5..5,
discontinuous=true));#jinak se nezobrazil graf druhe derivace
end:
animate(H9,[theta], theta=0..2*Pi,axes=none, title='_',
frames=50);

```



```

[ >
[ >
[ >

```